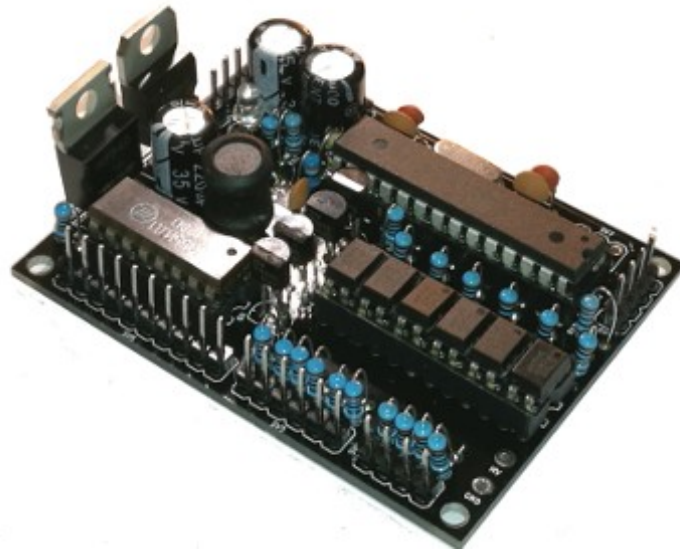


Arduino Nixie Clock

“Classic Revision 4”

Construction Manual

4 Digit Clock



About this document

This is the construction manual for the Classic Nixie Clock with 4 tubes instead of the usual 6. It covers how to build the clock shown above.

The same board can be used with either 4 or 6 tubes, the difference is in the components you install and the firmware on the board.

If you want to have the user operating manual, please find the appropriate version matching the firmware you are using (the clock will tell you on startup, and it should be marked on the packing slip you received) at:

<https://www.nixieclock.biz/Manuals.html>

Contact Information

If you want to get in contact with us, please email to:

nixie@protonmail.ch

We'll usually get back to you right away. We can help you with kits or construction.

We also offer discounts for direct purchases, we save the Ebay fees, and share this with you.

<http://www.nixieclock.biz/Store.html>

Software

The software is available on GitHub at the address:

<https://bitbucket.org/isparkes/nixiefirmwarev1>

The license of the software, hardware, schematics and documentation is Creative Commons CC-BY-NC. This means you are allowed to copy change and distribute the software, but are not allowed to make money from it.

Troubleshooting

If everything does not work as you expect, please carefully look at the tests in the construction steps, and the troubleshooting tips.

At the end of the manual, there is a troubleshooting section, which goes through some of the common problems.

There is also a forum where many problems have already been dealt with at:

<https://goo.gl/dQUYWx>

(redirects to <https://www.tubeclockdb.com/component/kunena/12-arduino-nixie-clock-kit-support-forum.html>)

You can also find other helpful people here!

Safety

The voltages produced in the High Voltage circuit can reach peaks of 400V! Take precautions not to electrocute yourself! If you are not sure what this means, please do not use this clock and return it for a full refund.

A shock from the clock high voltage circuit is at least a nasty bite. At worst it can kill you.

We decline any responsibility in the case of injury or death.

REPEAT: If you are not sure, please do not use the clock.

Powering Up

When you power the unit up for the first time, it will go into the startup test routine. This will set the High Voltage Generator to run with some default settings which are useful for the construction of the clock. For a full description of the startup sequence, please see the User Manual.

For a video of the startup process on a finished clock, please see:

<https://youtu.be/XA3LOPLX8vI>

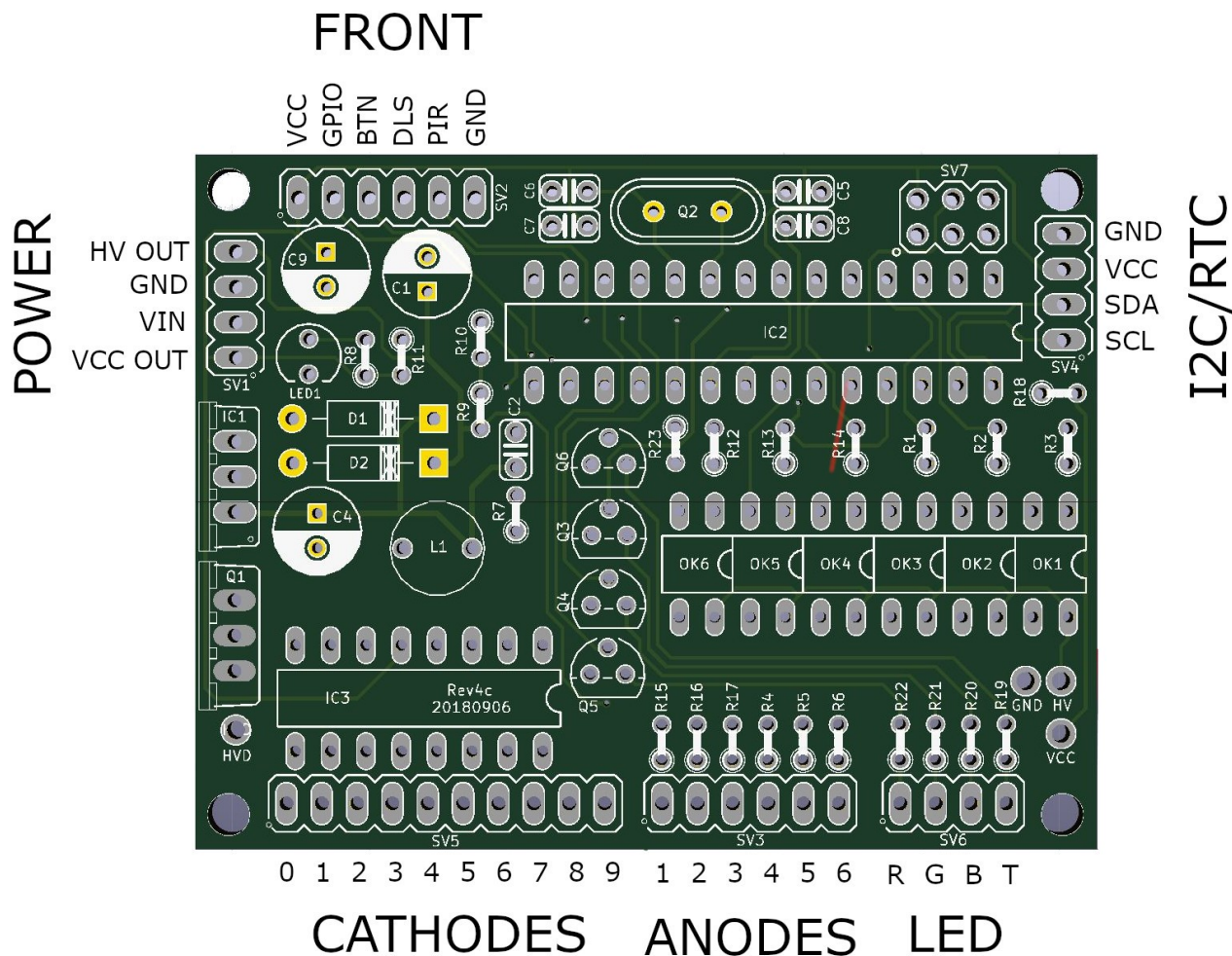
Component Identification

Sometimes it is hard to tell one component from another. Please see the “Component Identification” manual to help you tell one component from another. You can get this document here:

<https://www.nixieclock.biz/Manuals.html>

Board layout

For reference, the board layout is as shown (viewed from the top):



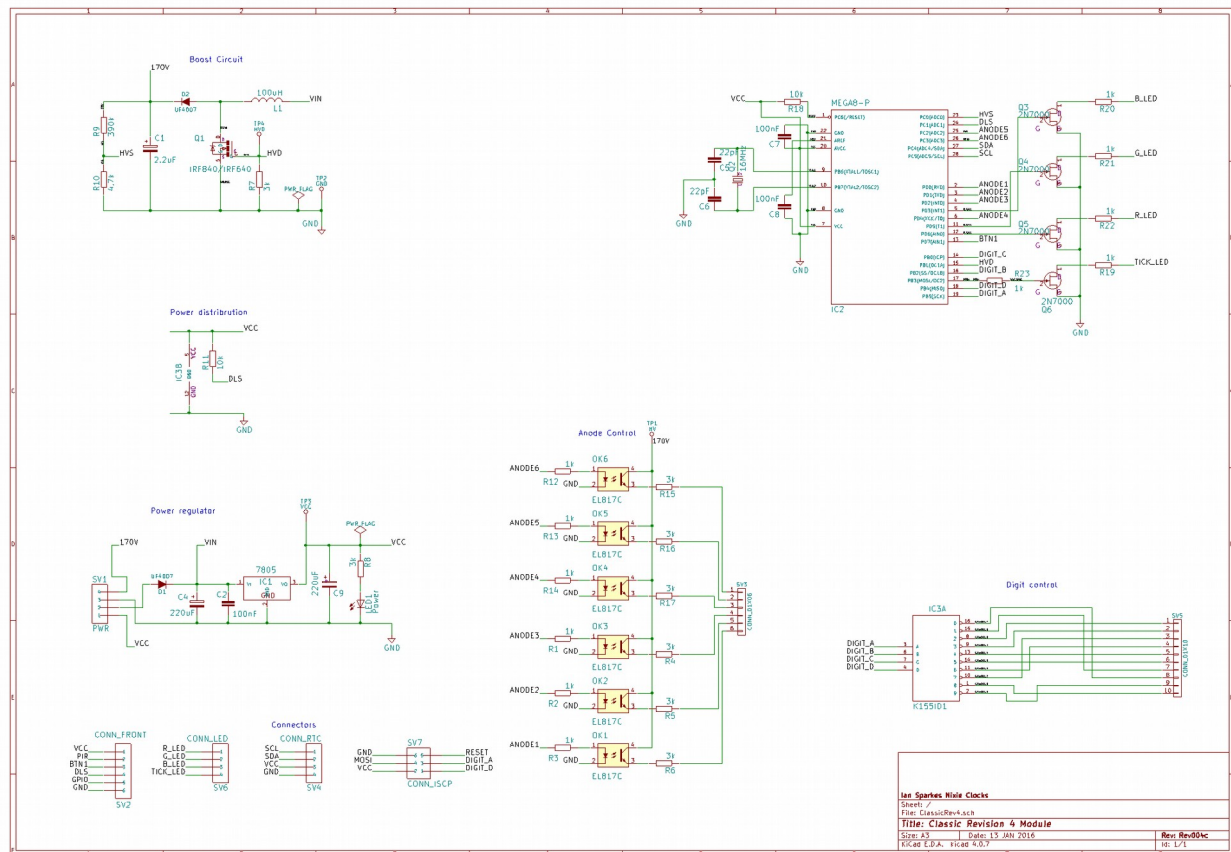
The connections are:

Connector	Description
POWER	<p>External power should be applied to the board with this connector. The best input is 9V DC. Higher voltages may be possible, but could cause the digits to flicker if the voltage is too high, and you might have to provide a heat sink for the MOSFET and voltage regulator.</p> <p>The absolute maximum input voltage is 16V. Any higher voltage than this will damage the board within a few seconds!</p> <p>The input VIN is protected against the input being connected reversed.</p> <p>The input current ranges from 300mA to 1A depending on the size of the tubes and the number of LEDs you are driving.</p> <p>GND: The negative side of the input supply VIN: The positive side of the input supply VCC: Output of regulated 5V HV OUT: Output of high voltage for driving external neons etc.</p>

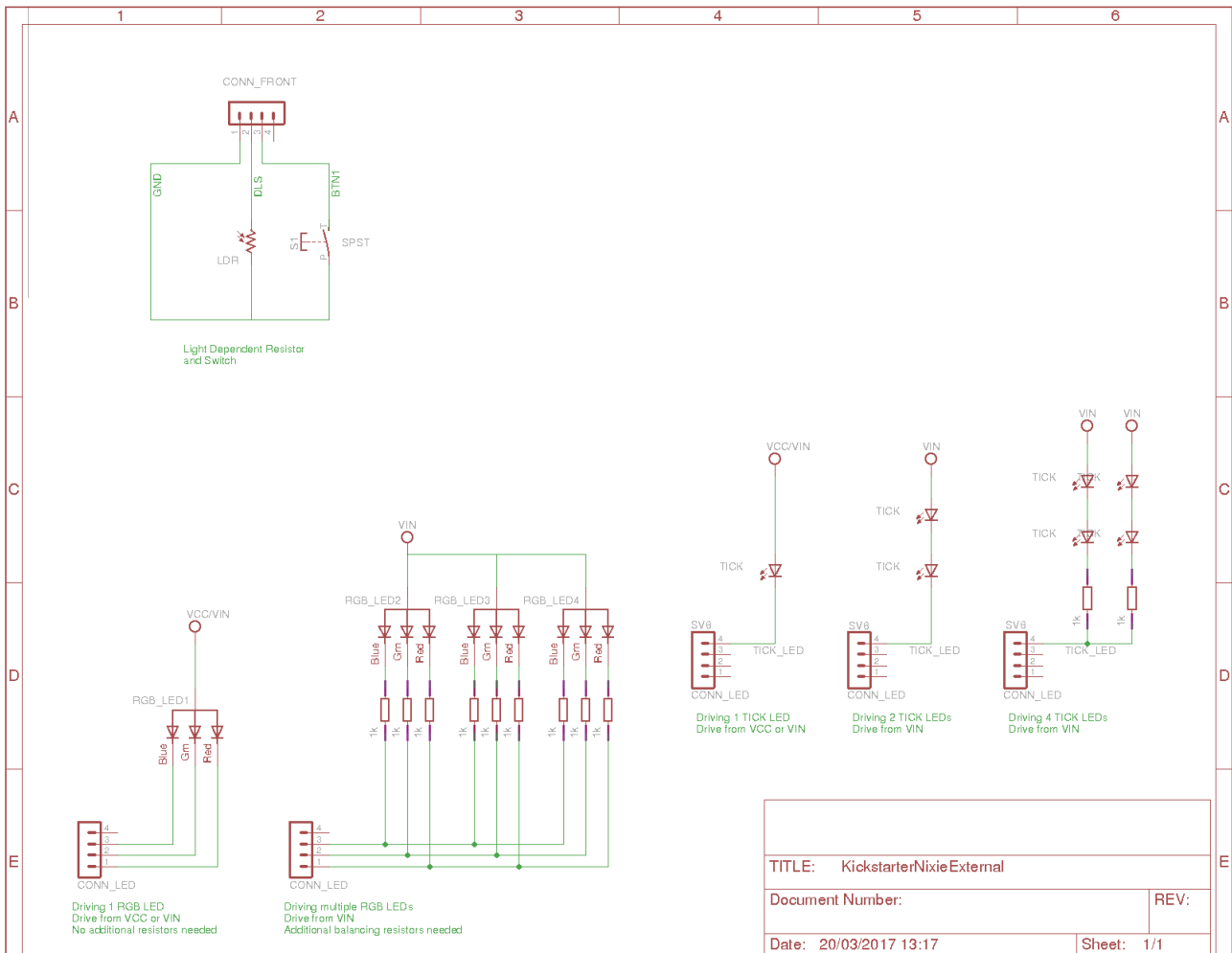
Connector	Description
FRONT	<p>These are the controls that go on the front panel: The input button and the Light Dependent Resistor to detect ambient light.</p> <p>GND: The “ground”. One lead of the button and one lead of the LDR and one lead of the button are connected to this.</p> <p>BTN: The other lead of the button is connected to this input</p> <p>DLS: “Dimming LDR Sense”: The other lead of the LDR is connected to this</p> <p>VCC: Regulated 5V output to drive any LEDs or lighting. Note that you can also connect the LEDs to the VIN if you want to reduce the load of the regulator.</p> <p>PIR: Input for a PIR (Passive Infrared) or microwave motion detector. Note: Not available on 6 digit version!</p> <p>GPIO: General purpose GPIO input or output. Currently not used. Note: Not available on 6 digit version!</p>
LED	<p>The LEDs are connected to these <u>sink</u> (they consume current, not source it) terminals. To connect up you take the positive sides of the LEDs to either VIN or VCC and connect the negative sides of the LEDs to these terminals.</p> <p>R: PWM cathode connection for the back light RED channel.</p> <p>G: PWM cathode connection for the back light GREEN channel.</p> <p>B: PWM cathode connection for the back light BLUE channel.</p> <p>T: PWM Cathode connection for the blinking “tick” LED.</p>
RTC	<p>The connection for the RTC (Real Time Clock) or WiFi time provider module. Connect this to the appropriately marked terminals on the RTC / WIFI module.</p>
CATHODES	<p>The terminals to the cathodes (individual digits “0” - “9”) for each tube. Terminal “0” drives the cathode “0” and so on.</p>
ANODES	<p>The terminals to the anodes for each tube. The allocation of anode to tube is:</p> <ol style="list-style-type: none"> 1. Tens of hours 2. Hours 3. Tens of Minutes 4. Minutes 5. Tens of seconds 6. Seconds

Schematic

Below is the schematic for the clock.



And for the external components, showing how they are connected.



One side of the LDR and switch are connected to ground (pin 1, SV2).

The LEDs are driven from VCC or VIN, depending on the configuration. Here are some suggestions:

1 TICK LED:

Run the TICK LED directly from the board, either from VCC or VIN.

2 TICK LEDs:

Run the two TICK LEDs in series from VIN. You don't need a balancing resistor because the LEDs are in series.

4 TICK LEDs:

Run the TICK LEDs by putting 2 in series, and running the two series combinations in parallel. In this case you need a 1k balancing resistor in each series.

1 RGB Back Light LED:

Run the RGB LED directly from the board, either from VCC or VIN.

Multiple RGB Back Light LEDs:

Each RGB LED needs a series balancing resistor on each Red, Green and Blue cathode. I normally run 6 in this configuration.

Construction

Preparation:

You should have a small tipped soldering iron, some thin (< 1mm) solder, and electronic side cutters.

Kit Contents:

When you unpack the kit, you should find the following contents as listed in the BOM (Bill of Materials). It is best to check the contents before you start, and notify me straight away if you are missing any components.

Please see the appendix to help you identify individual components.

Low Voltage Circuit:

Parts List:

D1	UF4007
C2	100nF
C4	220uF 16V
C9	220uF 10V
IC1	7805
R8	3k
LED1	LED3MM
SV1	CONN_POWER

Video Build tutorial: https://youtu.be/ncfxmen_XHc

The Low Voltage circuit is a very traditional voltage regulator using a linear regulator. It's job is to reduce the external voltage from the power adapter down to a known and stable 5V to drive the micro-controller and the K155ID1.

Put the parts on the board in the marked locations in the order they appear on the list.

Notes:

- See the section on "Component Identification" for help with identifying the components.
- D1 should be placed so that the white stripe on the body lines up with the white stripe on the board.
- C4 and C9 must go the right way round. The negative side is marked with a stripe. (See hint). Note that C4 has a higher voltage rating than C9.
- The LED must go with the right polarity. The side which has the shorter lead goes nearest the diode. (See hint)
- Put IC1 so that the metal tab lines up with the white stripe on the board. The metal side faces to the *outside* of the board.



Test Step

Once all the components are on the board, hook up the power, and check that the power LED comes on.

Check also that the voltage is 5V between the “GND” test point and the “VCC” test point and at the power connector.



Trouble shooting

If the LED does not come on, turn off immediately to avoid damage to the components. Check your soldering and the polarity of the components.

If the components are in the right way, connect the power again, and check that the 7805 voltage regulator does not get hot. If it does not, measure the voltages in the low voltage circuit.

Measure the voltage at the input (“Vin”) and at the cathode side of D1 (nearest the centre of the board). This should measure 0.7V less than the input voltage.

If all is well, proceed to the next step. If not, check carefully the orientation of the components and the power leads. Diode D1 protects the board from having the power connected inverted.

If the LED comes on, check for a few seconds that the 7805 does not heat up. It should stay almost cold.

Hint: The 220 uF capacitor

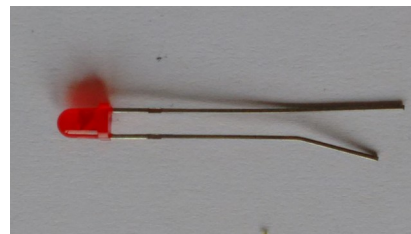
The electrolytic capacitor has a stripe on it to denote the **negative** side of the capacitor. The positive side of the capacitor (which goes into the “+” on the board) is the other one!



220uF capacitor “stripe”

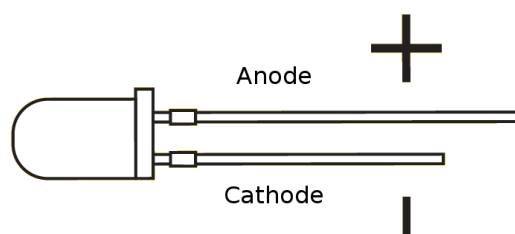
Hint: The LED orientation

The LED has one lead longer than the other, and a flat on one side. The side with the **shorter** lead (the cathode) goes into the hole on the board nearest the diode.

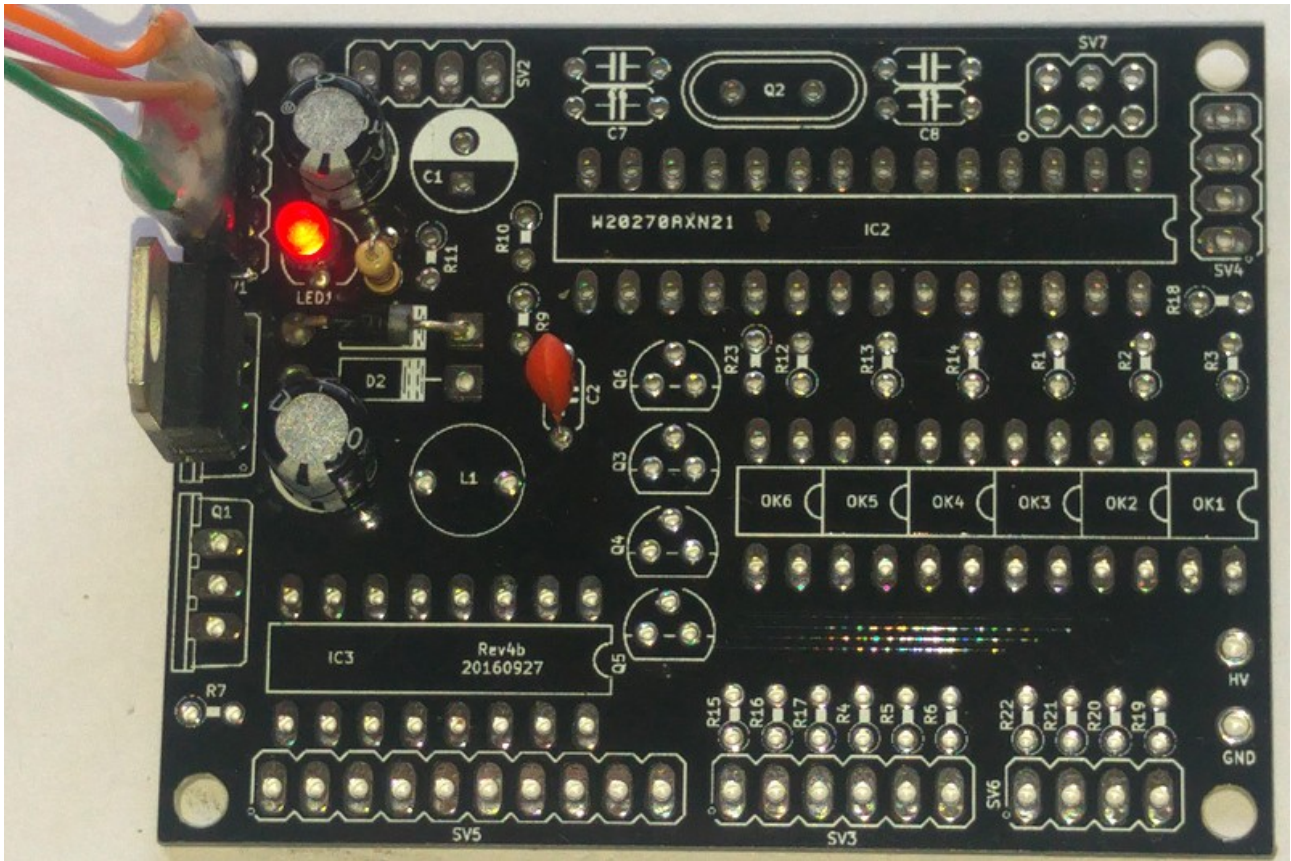


The LED

The LED should look something like this:



At the end of the low voltage circuit build, your board should look like this:



Low Voltage Circuit

Especially note the orientation of the electrolytic capacitors (white stripe) and the diodes (white stripe on D1 and the flat on LED1):



Low Voltage Circuit Component Orientation

High Voltage Circuit:

Parts List:

C5	22pF
C6	22pF
C1	2.2uF 400V
C7	100nF
C8	100nF
D2	UF4007
S28	SOCKET 28
Q2	16MHz
L1	100uH
R7	3k
Q1	IRF640
R9	390k
R10	4.7k
R18	10k
IC2	MEGA8-P

Video Build tutorial: <https://youtu.be/-uD9uV1gYw>

The high voltage circuit uses the micro-controller to drive the boost circuit with a high frequency square wave, and has a feedback loop in which the controller reads the voltage produced via an analogue input, and regulates the brightness of the tubes so that there is no flickering or unwanted dimming.

Notes:

- See the section on “Component Identification” for help with identifying the components.
- C1 must go the right way round. The negative side is marked with a stripe (see hint).
- Put Q1 so that the metal portion lines up with the white stripe on the board. The metal side faces to the outside of the board.
- D2 should be placed so that the white stripe on the body lines up with the white stripe on the board.
- Put the micro-controller socket in first. Make sure that the depression on the end of the socket lines up with the marking on the board. When you put the chip in, the chip should go in with the depression facing to the outside of the board.



Warning!

Check the orientation of the components before you proceed!

Especially the orientation of R9 and R10, as well as the electrolytic capacitor C1 is important. If you switch R9 and R10, you will put 170V into the micro-controller, and this will destroy it.

See the picture to help you with the orientation.

Once all the components are on the board, hook up the power. Give your work a careful check to make sure that the orientation of the components is right. Especially check that the stripe on C1 is facing the top of the board (not near the 170V test point).



Warning!

Be careful, we are dealing with high voltages now!

The voltage may be significantly higher than 170V at the moment, because the high voltage generator is powerful and the output is not loaded. Once you add a load, (by connecting the tubes), the voltage should oscillate around 170V – 190V, and might have a slight “sawtooth” appearance if you view it with an oscilloscope.



Test Step

Apply power to the board again. Listen for any stressed sounding buzzing or humming, and check that neither the 7805 nor the MOSFET get excessively hot.

Check that the power LED still lights.



Trouble
shooting

If you hear any angry sounding buzzing turn the power off immediately and check the orientation of C1! The circuit should run almost silently, with only a very faint “crackling” sound.

If you can't reach the target voltage, turn off and check the polarity of your components, especially C1. If you have an oscilloscope, you can check the voltage at the gate of the MOSFET, and it should show pulses of high frequency square wave: this is the driver waveform to the HV generator, which is being turned off and on by the voltage detection, trying to achieve the target voltage (180V default).



Warning!

Note also that the “Power” header also has high voltage exposed on it!

This is for if you want to drive neons instead of LEDs for the colons. Be careful handling the board, it is easy to touch the “Power” header by mistake. If you are sure you won't be needing it, you can snap the extra pin off and populate only the bottom 3 pins on the connector.



Test Step

Check the voltage at the 170V test point. You should read a voltage in excess of 170V.

You can also test using an old neon lamp if you have one. Temporarily connect the neon lamp between the “GND” test point and the “170V” test point with an appropriate ballast resistor (turn the power off first). Turn the power on and the neon lamp should come on.



Q1 can get warm, **but should not get too hot to touch**. If it gets hot, you need to check the orientation of the components and that there are no solder

Trouble
shooting

bridges.

If you don't get the expected voltage reading:

- Check your soldering that there are no bridges or dry joints.
- Check that the external power supply is able to supply the power needed to achieve the high voltage: check that the VIN voltage is stable and not fluctuating.
- Temporarily connect the button and do a factory reset. It could be that the controller has gone past test mode and is in clock run mode, which relies on the LDR, which we have not yet installed.



Trouble
shooting

The High Voltage generation works for a short time, and then stops. It might be the circuit is producing voltages which are far too high. In this case temporarily load the high voltage generator output with a tube and a series 3k resistor or just a 10k resistor (0.5W or more) and try again. (A tube is best, a resistor gets very hot and might be useless after the test).



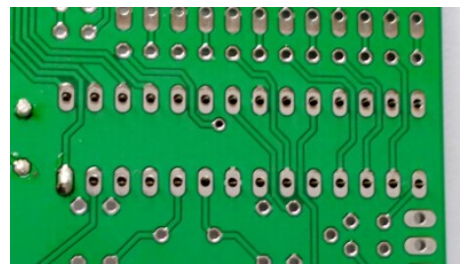
Warning!

Note that the high voltage generation in “Test Mode” only runs for 60 seconds at a time.

If you need longer to test your circuit, you will have to power off and on again to restart the timer. This is because the high voltage generator runs with no feed back loop, and can cause the high voltage circuit to overheat if left running in this mode for a long time.

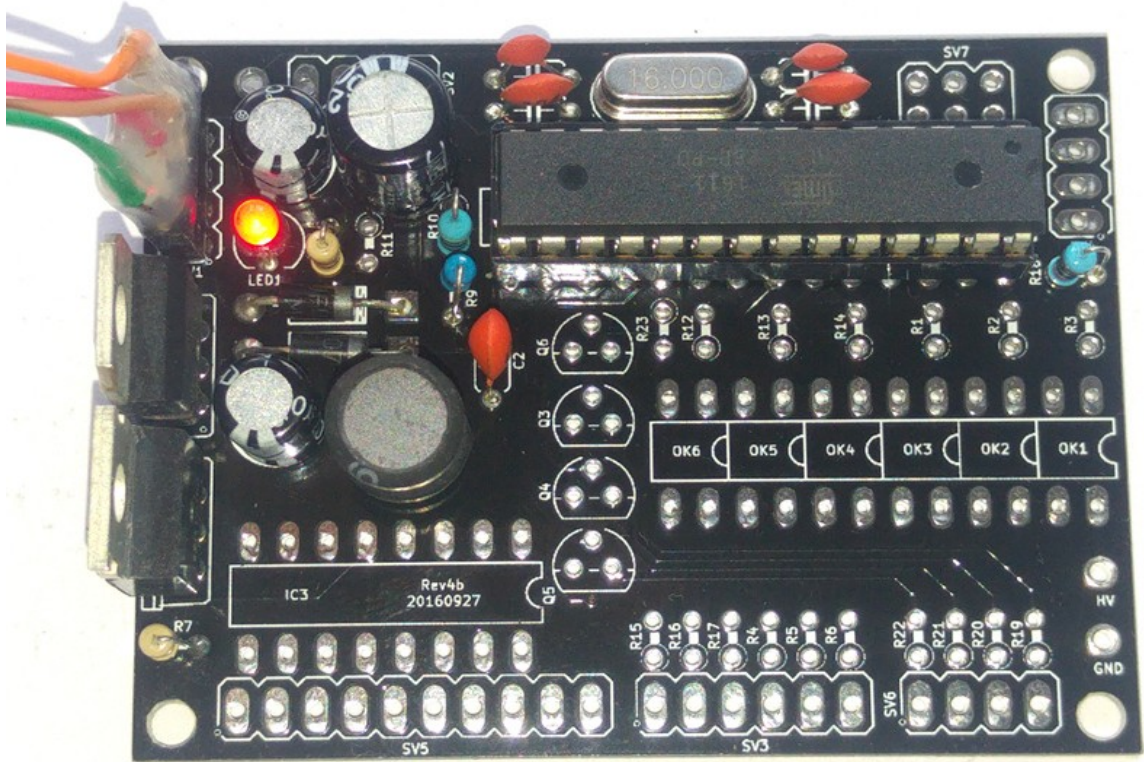
Hint: Mounting the 28 pin socket

Mounting the 28 pin socket can be a little difficult. A good trick is to fix it in place with a small piece of tape, and the solder one leg in place. You can hold the socket firm while you “wet” the solder again, which will hold the socket firmly enough to solder the remaining pins. One leg is usually enough to hold the socket in place while you solder the others.



Mounting 28 pin socket

At the end of the high voltage circuit build, your board should look like this:



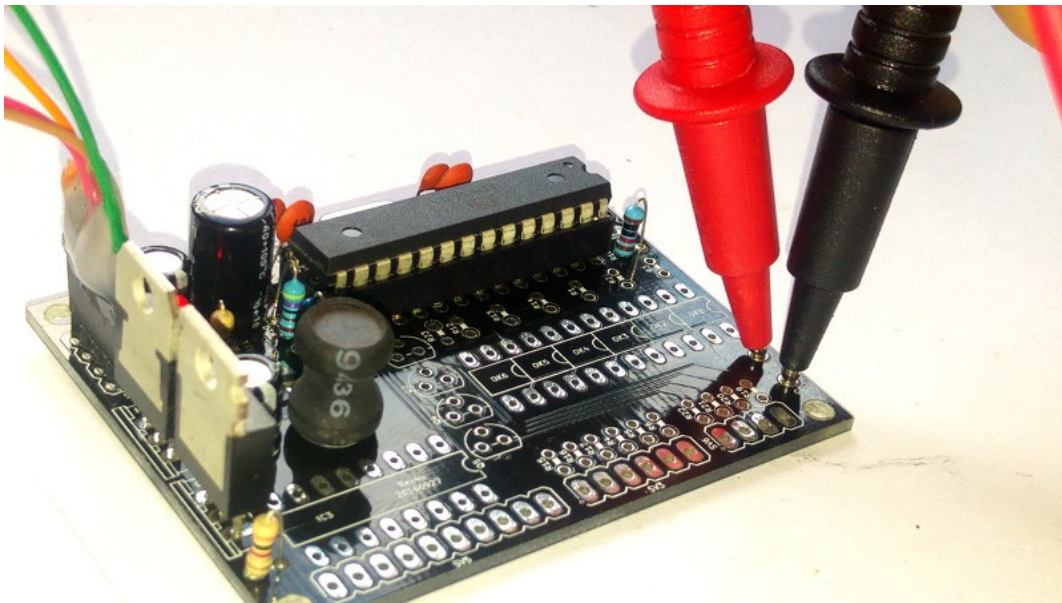
High Voltage Circuit

Here is a close up of the high voltage circuit:



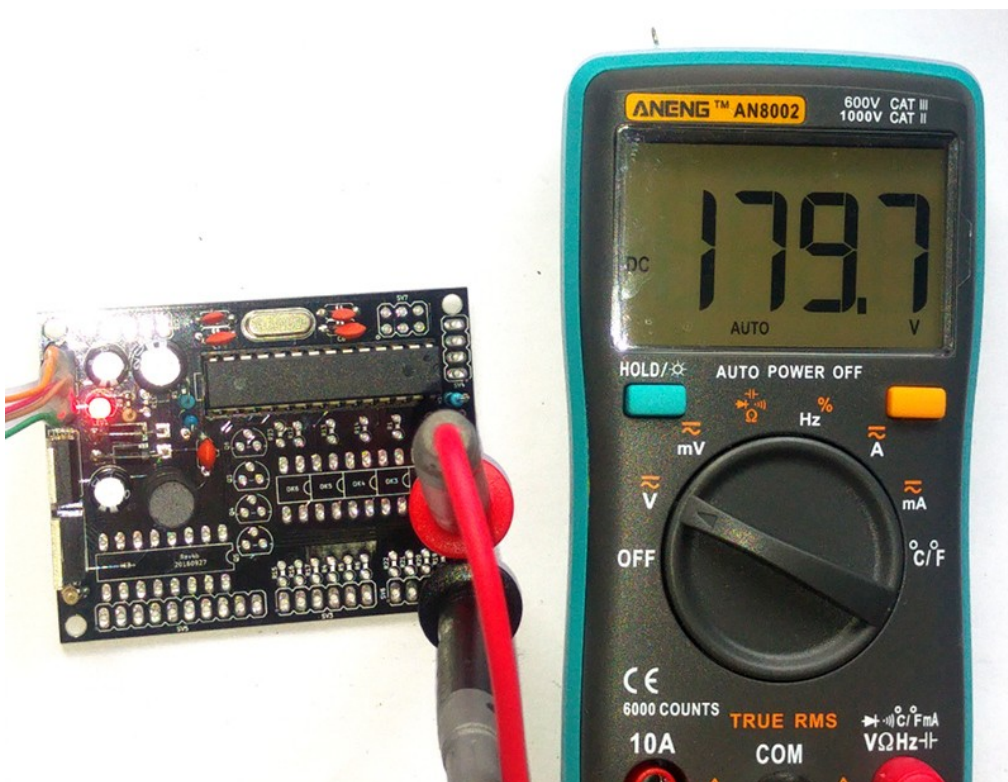
High Voltage Circuit Detail

here is where to measure the voltage:



High Voltage Circuit Test Points

And finally the test voltage. Note that this may start higher, but should settle at about 180V:



High Voltage Circuit Detail

Anode Control Circuit:

Parts List:

S24	SOCKET 24
OK1	EL817
OK2	EL817
OK3	EL817
OK4	EL817
OK5	Do not install
OK6	Do not install
R1	1k
R2	1k
R3	1k
R12	Do not install
R13	Do not install
R14	1k
R4	3k
R5	3k
R6	3k
R15	Do not install
R16	Do not install
R17	3k
SV3	CONN_ANODE

This circuit controls passing the HV to the anodes of the tubes. The micro-controller multiplexes the anodes by turning each of them on it turn for a very short period of time. The software controls the rate of the multiplexing and the order in which the anodes are activated.

Notes:

- The Opto-Isolators fit into the 24 pin socket snugly. Be careful to put them in the right way round. The dot denotes pin 1 and should be on the side closest to the micro-controller. All 6 should fit perfectly into the 24 pin socket.
- The Opto-Isolators are socketed because they are sensitive to heat and are easily destroyed if you apply too much heat to them. Putting them in a socket means that we don't run the risk of destroying them while soldering.
- If you receive the connector header as a single strip, break off 6 pins for SV3.

Hint: Putting the resistors in

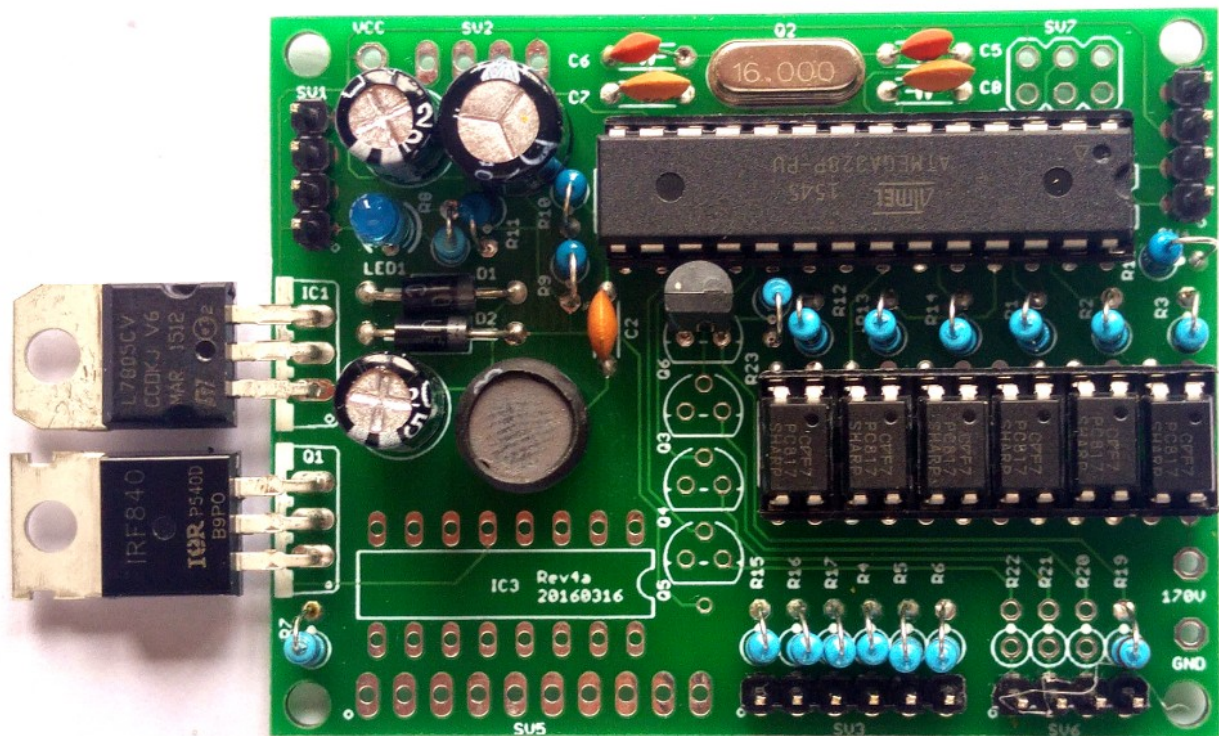
A trick that can speed assembly up is to use a piece of normal sticky tape to hold things in place while you solder them. This makes it easier to solder and gives a better result.

Place the components, and then temporarily tape them into place.



Using tape to hold resistors in place

After you have installed the Anode controls, the board should look this:



Cathode Control Circuit:

Parts List:

IC3	K155ID1
S16	SOCKET 16
SV5	CONN_DIGIT

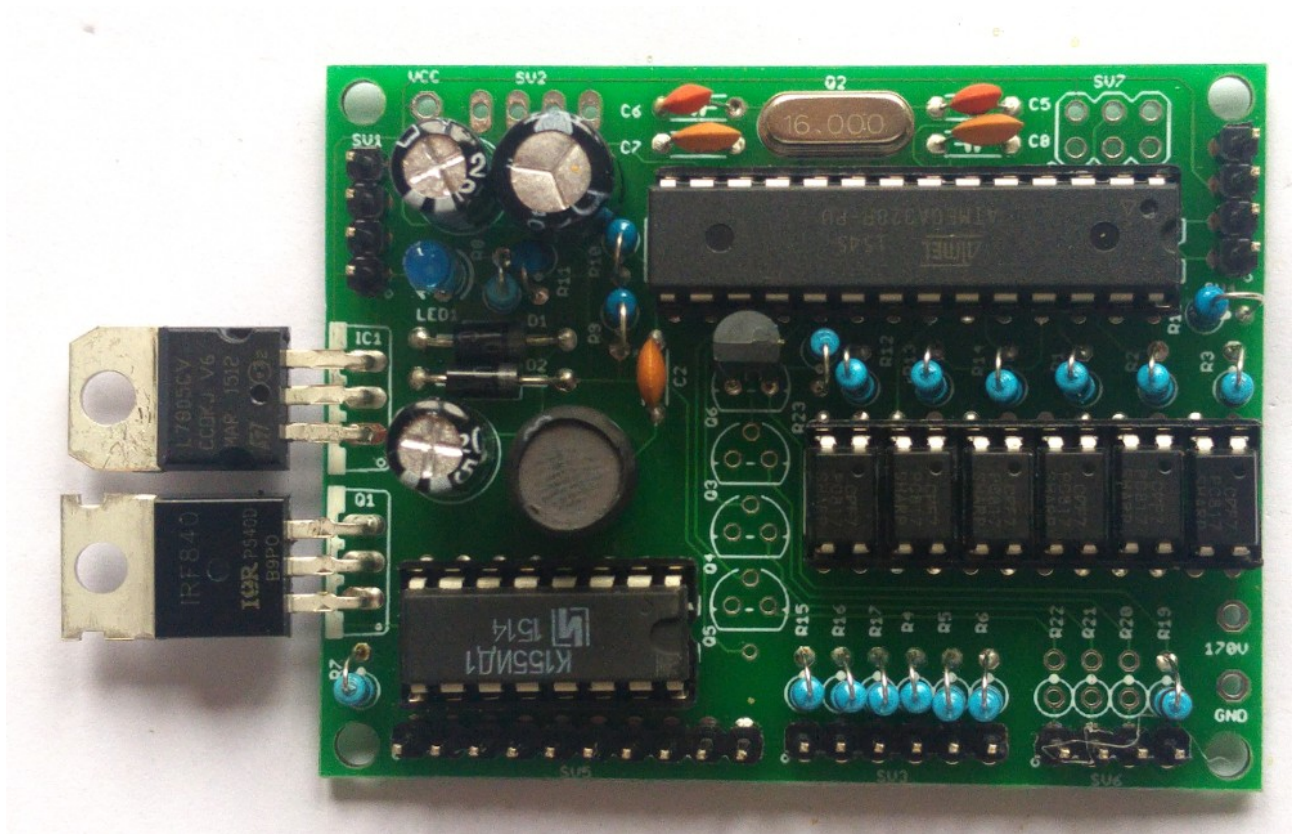
This part of the circuit controls which cathode will be lit. Each time the digit to be displayed, the correct cathodes have to be set.

Notes:

- Instead of the 74141, you might have the Russian equivalent "K155".
- Be careful to orient the 74141 correctly
- If you receive the connector header as a single strip, break off 10 pins for SV4.

Place the 16 pin socket and the connector, and then put the cathode driver on the board.

After you have done this, the board should look like this:



LEDs and front panel

Parts List:

R19	1k
R20	1k (*)
R21	1k (*)
R22	1k (*)
R23	1k
Q3	2N7000
Q4	2N7000
Q5	2N7000
Q6	MPSA42
SV6	CONN_LED
SV4	CONN_RTC
R11	10k
LED RGB	LED RGB Common anode
TICK LED	LED 5mm (off board)
LDR	GL5516
S1	SWITCH

These are the final parts of the clock apart from the tubes, and are intended as the elements which the user sees and touches.

This is the last step of the main board build.

Notes:

- If you want to have two LEDs for the “tick” circuit, you can place these in series, and power them from the unregulated VIN voltage.
- The FETs should be orientated with the flat side as shown on the board. Some FETs come with the leads in a row rather than in a triangle. If this is the case, bend the middle lead slightly so that it fits the holes in the board (see hint).
- If you want to run more than one back light LED from the board, see the note below.
- The LDR is connected between pin 1 (GND) and pin 4 (DLS) of SV2.
- R11 is needed to bias the LDR ambient light detection circuit, to make sure that the LED lights up reliably.
- The switch is connected between pin 1 (GND) and pin 3 (BTN1) of SV2.
- The RGB LED has a flat on one side and one lead longer than the rest. The common anode is the longest pin. The Red cathode is next to the flat on the case. The green is next to the anode, and the blue is on the side farthest from the flat.
- The RGB LED anode is connected to pin 4 (VCC) of SV2. Red is connected to pin 1 of SV6, green to pin 2 of SV6 and blue to pin 3 of SV6.
- The LED must go with the right polarity. The “-” side has a flat on it, and has the shorter lead (see hint), and must be connected to pin 4 of SV6.

- If you receive the connector header as a single strip, break off 4 pins for SV6 and 4 pins for SV2.

The LED should be wired up with the longer lead to pin 4 of the CONN_FRONT (SV2) connector and the shorter lead to pin 4 of the CONN_LED (SV6) connector. (Pin 1 has a little “o” beside it on each connector on the board).



Test Step

Once you have populated the components, power on. The LED on the RTC module should come on, and the “TICK” LED should flash on and off slowly (on for one second, off for one second). It might take a second or two to come on, but after that should “pulse” on and off.



Trouble shooting

If the LED does not flash at all:

- Check that the LED is the right polarity
- Check that you have sourced the voltage for the LED anode from VIN
- Note that the LED driver is an open collector circuit, and will not show any voltage if the LED is not connected, or connected in the wrong polarity.



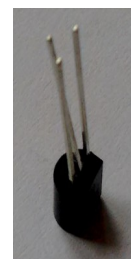
Trouble shooting

If the LED flashes, but with the wrong rhythm:

- If you see one second on, one second off, perform a factory reset. The controller has gone past the start up sequence and we should reset it (Note this comment is valid only for firmware version V48 and later).

Hint: MPSA42/2N7000 mounting

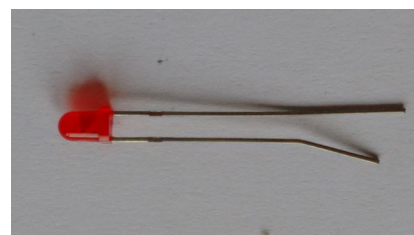
To mount the MSPA 42 transistor or 2N7000 FET, bend the middle lead back slightly. It will then fit in the PCB without problems.



MPSA42/2N7000

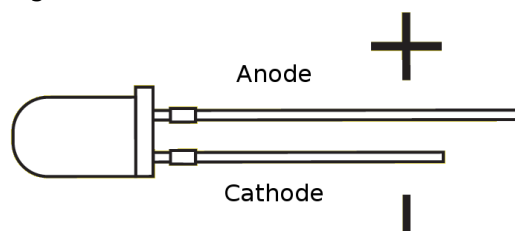
Hint: The LED orientation

The LED has one lead longer than the other, and a flat on one side. The side with the **longer** lead (the anode) goes into the hole on the board nearest the VCC test point.



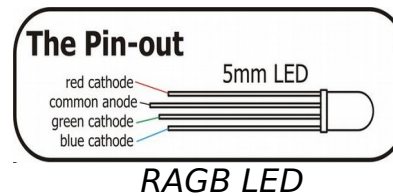
The LED

The LED should look something like this:



Hint: RGB LED pin put

The RGB LED is a Common Anode LED (also known as RAGB), which has one pin longer than the others. The longest pin is the common anode pin.



(*) You can run more than one back light LED for each R,G or B channel. If you want to do this, replace this resistor with a simple PCB link, and put a 1k resistor in series with each LED cathode instead. You can run between 4 and 6 LEDs off the driver depending on the type and the supply (you can choose the regulated 5V or the unregulated VIN). The total current for each channel should not exceed 200mA.

Often, when running from VIN, you can leave the 1K resistor on the board and additionally place a 1K resistor in series with each LED cathode.

Likewise, you can run two TICK LEDs in series from VIN with the 1K resistor on the board.

Calculate the current consumption of the LEDs

If you want to drive multiple LEDs or want to run the LEDs from VIN, please check the current consumption. It is very easy.

To calculate the current drawn, you can measure the forward drop V_{FWD} across the LED when it is on, and use the following formula to calculate the current:

$$I_{LED} = V_{CC} - V_{FWD} / 1k$$

For example, with a V_{FWD} of 2.2V, the current is:

$$I_{LED} = 5 - 2.2 / 1k = 2.8mA$$

In this case, you can safely run 6 LEDs off the channel.

Front Panel components

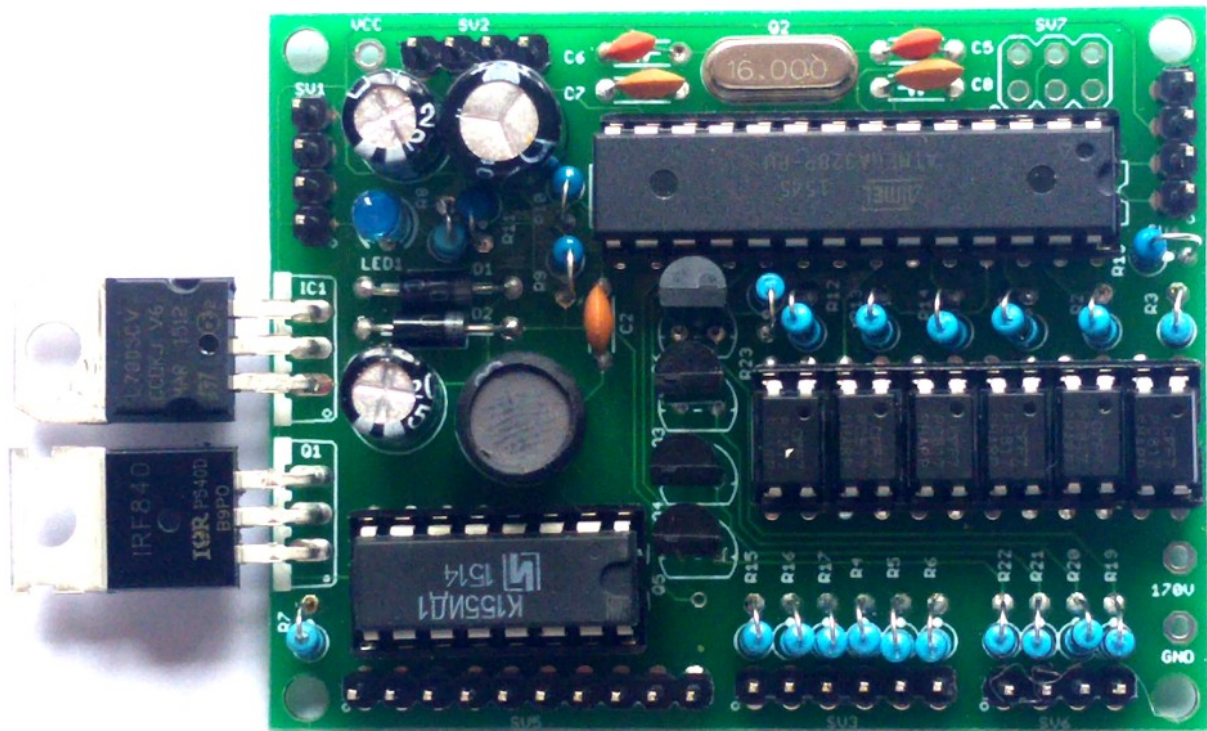
When all the components are installed, you are finished with the main board.

The switch connects to ground when closed. It uses the internal pull-up resistor provided by the Atmega on the input pin to pull the input to VCC when the switch is not closed.

The switch is de-bounced in software, so practically any switch you want to use is suitable. A simple switch is provided in the kit, but you might want to substitute this switch with one that suits your case.

The LDR should be mounted in such a way that the flat face of the LDR is exposed to the ambient light. This will allow it to detect the ambient light and adjust the brightness for it.

The finished module should look like this:



Time Provider

Parts list:

RTC	Real Time Clock Module
WiFi	WiFi module
SV3	CONN_RTC

You should connect the RTC module or the WiFi module, but not both. The pin out is the same for both.

The clock needs to know the time. To do this, an RTC or WiFi module is supplied with the kit, (depending on the option you chose). You can mount these modules directly on the board, or as a separate board connected by flying leads.

The markings on the board need to match up with the markings on the module. In particular, the VCC and GND need to be in the right orientation.

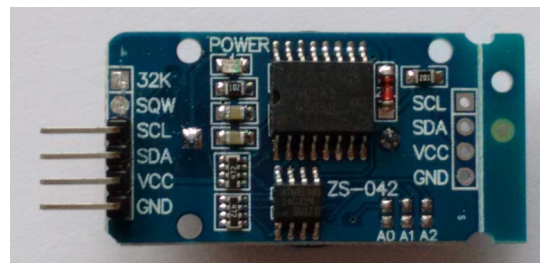
The WiFi module has it's own instruction manual. Please refer to that if you have the WiFi option.

- The RTC module has two sets of contacts on it. You can use either the side with the pins on it or wire up the other side with flying wires. If you use the side with pins, you should carefully remove the two unused pins (see hint).

Hint: Trimming the extra pins on the RTC module

ONLY if you want to mount the RTC module directly onto the main board (you can also do it via flying leads), trim off the pins "32K" and "SQW" using a pair of precision side cutters.

If you want to mount using flying leads, you can skip this step and use the four holes on the other side of the board.



RTC Module with pins removed

The WiFi module has the pins in the same order and same markings as the RTC module, and can be connected in the same way. Please see the WiFi module manual for more information on how to use it.

Connecting the tubes

When all the components are installed, you are now ready to install the tubes. Either you can wire them by hand or you have a board to put them on. I prefer hand wiring, because I think it has a more “retro” feel.

The anodes are arranged like this:

Anode “1”	Hours 10s
Anode “2”	Hours
Anode “3”	Minutes 10s
Anode “4”	Minutes
Anode “5”	Seconds 10s
Anode “6”	Seconds

Anode “1” is the one next to the tiny “o” printed on the board next to the connector.

The cathodes are arranged like this:

Cathode “0”	Digit 0
Cathode “1”	Digit 1
Cathode “2”	Digit 2
Cathode “3”	Digit 3
Cathode “4”	Digit 4
Cathode “5”	Digit 5
Cathode “6”	Digit 6
Cathode “7”	Digit 7
Cathode “8”	Digit 8
Cathode “9”	Digit 9

Cathode “0” is next to the tiny “o” printed on the board next to the connector.

Side note: There are some tricks in the software to make the wiring and the PCB easy and logical. We use a translation table in the software, and cross some of the standard channels to make the PCB more logical. You can also see this on the “digit control” section of the schematic. This means that we are not using the 74141 “0” output to drive digit “0”, but instead we are using digit “2” of the 74141 to drive digit “0”.

In the code (available on GitHub), we see this:

```
// Used for special mappings of the 74141 -> digit (wiring aid)
// allows the board wiring to be much simpler<
int decodeDigit[16] = {2,3,7,6,4,5,1,0,9,8,10,10,10,10,10,10};
```

When we come in with a “0”, we decode this to “2” (the 0th element of the array), and in fact, it is the “2” output that is activated, but the wiring brings the “2” output to the “0” connection.

The cathodes to the tubes (the digits for each tube) need to be wired in parallel, “daisy chaining” them, so that they run to the same digit of each tube.

The anodes run exactly one tube each.

Tube wiring

If you bought a kit without a display board, there is the task of wiring the tubes to be done. It can take a long time, but if you do it carefully, it can give a very beautiful “retro” feel.

There are a number of small tricks to make the task easier and the result better:

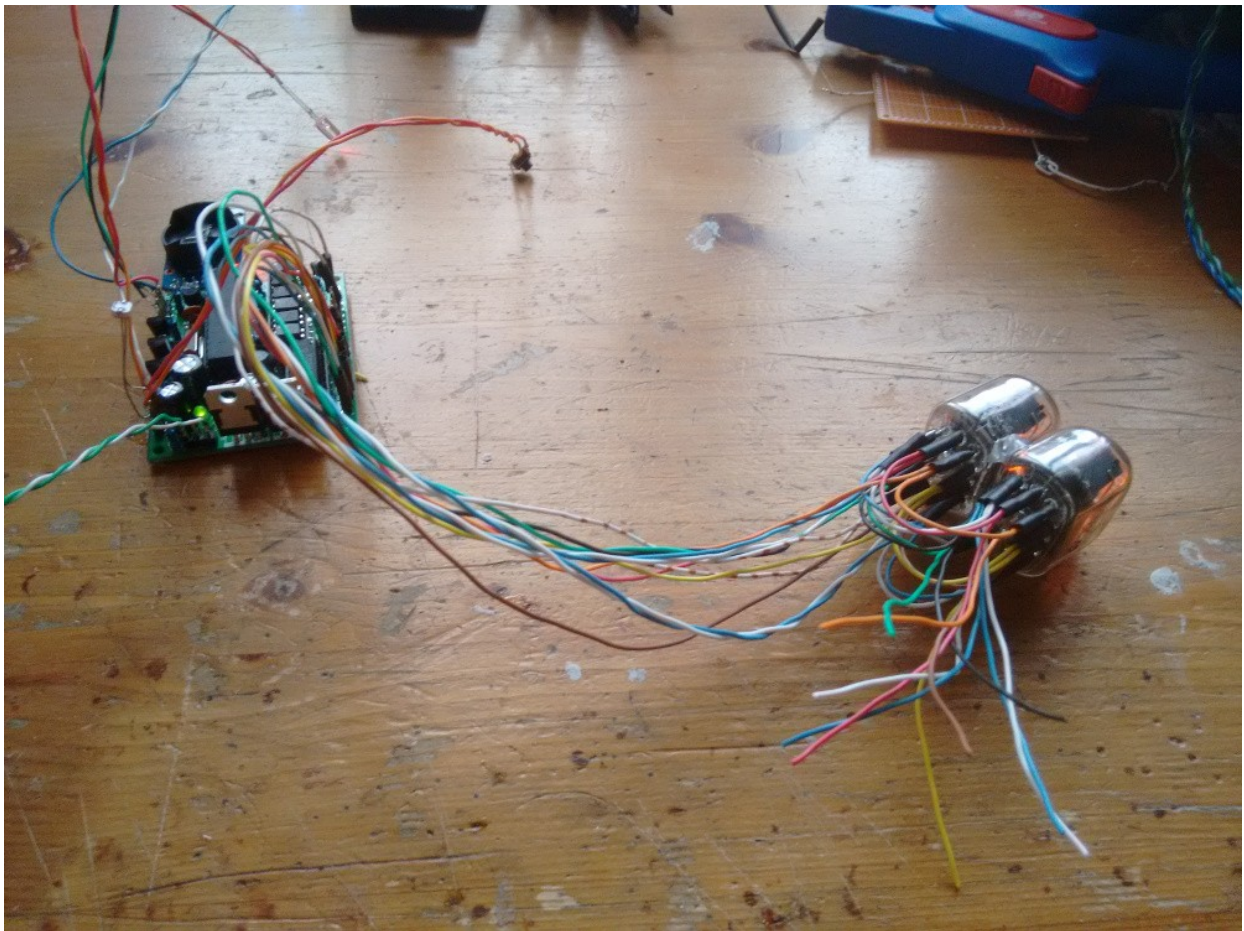
- Plan how long you want the lead to the board to be and how far apart the groups of digits “hours”, “minutes” and “seconds” should be.
- Temporarily either glue, tape or bind together the groups of digits while you are working on them. Later you can choose to substitute the temporary binding, or keep it if you wish.
- If you use heat shrink, do not shrink it until the end of the wiring. The reason for this is that we will complete the loom at the end, and will need to disconnect the board from the loom to tidy it up. Also for the identification of errors, it is useful to be able to switch or disconnect connections.
- Pre-cut the wires you are going to use, use different colors for each cathode or anode if possible. Keep the same color for each cathode as you proceed through the wiring. Make sure that all the wires for each task are the same length. The main wire tasks are:
 - Flying cathode connections (recommended 30cm):
 - 10 x flying cathodes from the board to the tubes
 - 6 x flying anodes from the board to the tubes
 - Intra group cathode connections (recommended 7cm):
 - 3 x 10 x cathodes
 - Inter group cathode connections (recommended 7cm):
 - 2 x 10 x cathodes
 - Flying anode connections (recommended 40cm):
 - 6 x flying anodes from the board to the tubes
- Wire anode 6 and anode 5 to the first group (“seconds”) from the board to the tube. Always make the flying lead connect to tube 6 first, then tube 5. This means our connection loom will come out at tube 6.
- Wire cathode “0” and cathode “1” from the board to tube 6 and daisy chain to tube 5. Prepare the daisy chain connection to the next group but **do not strip** the wire to the next group yet.

- You should have a result like this:



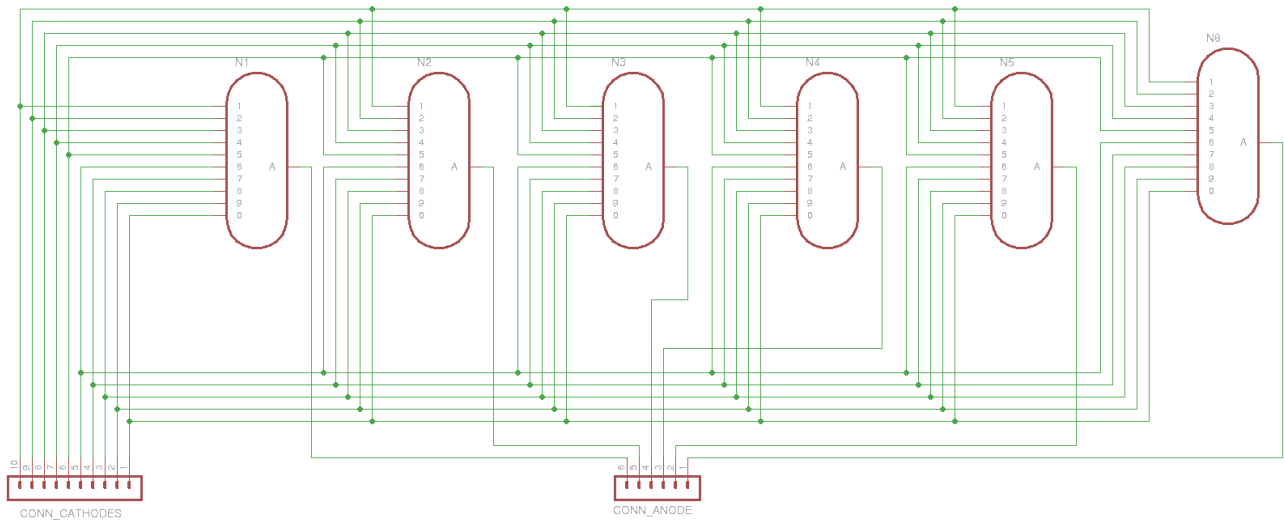
- Turn on the clock and check that you can clearly see the digits “0” and then “1” light up in sequence on the seconds tube every 10 seconds. Don't worry if there is “ghosting” on other digits at the moment – this will resolve itself as you connect more tubes and digits. (There are still a lot of floating connections at this point in the build and we are not loading the HV generator properly).
- Proceed to the other cathodes in turn, each time leaving the unstripped lead to the next group hanging.
- Try to pick an order you connect the tube cathodes in, and stick to it. This will give the wiring a “regular” feel. If there are any tangles or crossovers in the wiring, resolve them before soldering the wire in place.

- After you connected all the wires of the seconds group, you should have a result that looks like this:

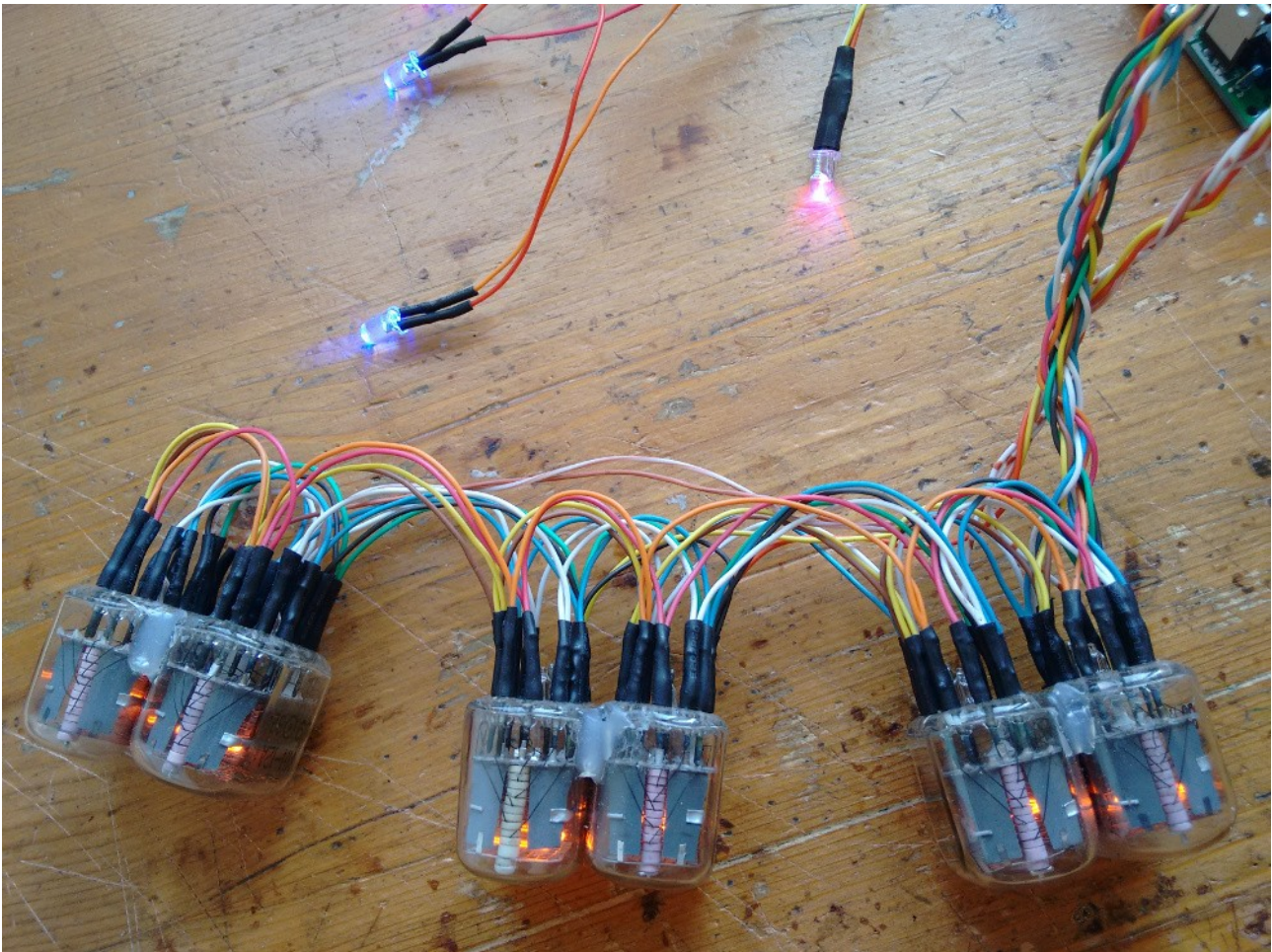


- Turn the clock on, and you should now see the seconds counting correctly.
- Complete the other groups in the same way, keeping the cathode connection colors and the order in which you connect them the same.
- At the end of the connection process, we want to “loom” the wiring. This involves binding and/or plaiting the wires to make them regular. For this you will need to disconnect the wires from the board. Make a note of the colors of each of the cathodes and anodes, because we will need to reconnect them in the same way.
- I usually plait the 6 anodes together in 3 groups two wires each, and the 10 cathodes in 5 groups of two wires. 3 plaiting and 5 plaiting can be found on YouTube. It is optional to plait the wires and simply binding them gives a good result as well.

The wiring for the tubes is this:



Here is a picture of a plaited loom in action. This particular version of the clock has two blue “tick” LEDs in series and three RGB LEDs (one for each digit group):



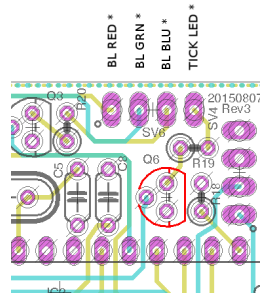
Hacks and alternatives

There are a number of options which can be built into the board easily.

Using Neons instead of LEDs for the “Tick” LED.

This is a very simple modification. Q6 is a high voltage MPSA42. The MPSA42 transistor has a compatible pin out to the FET (drain = collector, gate = base, source = emitter), but can withstand 300V.

This means that you can connect a neon indicator (with a ballast resistor) instead of LED(s).



This gives a more “retro” feel to the result.

For each neon, place a 56-100k resistor in series, and drive from the HV output on the power connector on the board. Here is an example with a 56k resistor and two INS-1 neons:



Driving 2 neons from the “Tick” circuit

Troubleshooting

If not everything goes as you expect, please refer to the test steps during the construction and the associated troubleshooting tips. If that does not cover the problem you have, please see below. If you still can't find the answer, contact us!



Trouble
shooting

The tubes flash (or blink) on and off.

This could be a symptom that the external power supply can't deliver the power needed to drive the circuit.

On start up, the High Voltage generator needs to draw significantly more power than when it is running normally, and in some cases this might overload the external power supply.

Try a different external power supply and see if the problem persists.



Trouble
shooting

The tube display brightness is not constant, and appears to “pulse” rapidly.

This is a symptom that the High Voltage generator or the external power supply is overloaded.

First perform a factory reset to make sure that no strange values have been left in the EEPROM.

Next, check the value of the **PWM On Time** configuration. Try increasing this until the brightness is constant, but be careful not to set the value too high. The longer the On Time, the more the MOSFET has to conduct current, and this will cause it to heat up. A good value for small tubes is 120-150, larger tubes may require 150-200.



Trouble
shooting

The display is too dim.

Check if the auto-dimming is working. If the display does not change in low or high ambient light, your LDR does not appear to be working. Check the connections to the LDR.

If the LDR is correct, perform a factory reset to make sure that no strange values have been left in the EEPROM.

Check the LDR reading by pressing the button three times in quick succession. You should see a value between “01 00 00” and “09 99 00”. Changing the light conditions should change this value. It is normal that the value is not stable when it is in the middle of the range. We read the LDR many times a second, and it is unusual that two readings are identical.



Trouble
shooting

The display does not come on, but I do have a high voltage.

Try pressing the button. If the display comes on, you probably have display blanking mode set. Check the configuration.

Check the orientation of the opto-couplers.

Check the LDR connection. In some cases, the dimming algorithm does not start

up as expected when no LDR is present. Shine a bright light on the LDR.
In some cases, a factory reset can help.



Trouble
shooting

No high voltage, but nothing gets really hot. LDR attached

Check that the LDR is connected between GND and the correct pin, and the connections have not been reversed with VCC (also on the same connector) and the BTN pin. One symptom is when you press the button the digits light up brightly.



Trouble
shooting

The MOSFET gets really hot.

Try a factory reset. There is a setting about how hard the IRF740 should be driven “PWM On Time”. Perhaps the value has not been set properly. The default value should be OK most of the time, but depending on the tubes and power supply, this might need adjustment. The lower the value, the less power will be used and the less hot the MOSFET will run, but also the less power will be available to drive the tubes.

Check the power supply. If the power supply is too “strong” (too much voltage or too much current capacity), the MOSFET will have to carry high currents. Try a different power supply. 9V and 500mA is ideal.

Change the settings for the “PWM On Time”. Adjust it to be as small as possible without a loss of brightness. This also reduces the power consumption of the module: normally it should not consume more than 3W.



Trouble
shooting

The MOSFET gets really hot.

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Change the settings for the “PWM On Time”. Adjust it to be as small as possible without a loss of brightness. This also reduces the power consumption of the module: normally it should not consume more than 3W.



Trouble
shooting

I can see some “ghosting”.

“Ghosting” is where you can see a very faint image of another number at the same time as the one that should be shown. Some tubes are more sensitive than others, and depending on the construction and components, it might show up more.

If you see ghosting, increase the “anti-ghosting” setting, but only to the point where the ghosting is no longer visible or irritating.

The “anti-ghosting” setting decreases the overall brightness of the display slightly, and not all tubes (even of the same sort) need it, so anti-ghosting should only be used when there is a real need to use it.

Programming the micro-controller

The micro-controller comes preprogrammed. You don't **need** to program it, but you might want to.

You can update the micro-controller with a newer version of the software, or even create your own software, and load it onto the chip. We have gone to a lot of trouble to make this as easy as possible.

Programming with an Arduino Uno

We supply the 328P micro-controller chips with a standard Arduino boot loader, so you don't need to have a special programmer in order to update the software, a standard Arduino UNO is enough.

To program the 328P, simply remove it from the clock board, and place it in the Arduino UNO. Then you will be able to program the controller as you would any other Arduino UNO, simply upload the software onto the controller. Put the 328P back into the clock board and you are done.

You can also program the 328P micro-controller with a programmer, but you will lose the possibility to program in the Arduino UNO, unless you remember to burn the boot loader again.

That's it!

Programming with ICSP (In Circuit Serial Programming)

As of Rev4, there is also an ICSP header socket provided on the board. This means that you can program the micro-controller without even removing it from the board. For this however, you do need to have a suitable programmer. If you intend to use ICSP, you need to populate the header.

Programming this way is extremely simple. Plug the 6 pin ISCP programmer cable into the header (pin 1 is nearest the micro-controller) and upload the program as you would with any other ICSP target.

Parts list / BOM

Here is the list of the parts needed

Note: If you find 3k resistors hard to find, 2k7 will do just as well.

Low Voltage Circuit

PCB	PCB	<input type="checkbox"/>
D1	UF4007	<input type="checkbox"/>
C2	100nF	<input type="checkbox"/>
C4	220uF 16V	<input type="checkbox"/>
IC1	7805	<input type="checkbox"/>
C9	220uF 10V	<input type="checkbox"/>
R8	3k	<input type="checkbox"/>
LED1	LED3MM	<input type="checkbox"/>
SV1	CONN_PWR	<input type="checkbox"/>

High Voltage Circuit

C5	22pF	<input type="checkbox"/>
C6	22pF	<input type="checkbox"/>
C1	2.2uF 400V	<input type="checkbox"/>
C7	100nF	<input type="checkbox"/>
C8	100nF	<input type="checkbox"/>
D2	UF4007	<input type="checkbox"/>
S28	SOCKET 28	<input type="checkbox"/>
Q2	16MHz	<input type="checkbox"/>
L1	100uH	<input type="checkbox"/>
R7	3k	<input type="checkbox"/>
Q1	IRF640	<input type="checkbox"/>
R9	390k	<input type="checkbox"/>
R10	4.7k	<input type="checkbox"/>
R18	10k	<input type="checkbox"/>
IC2	MEGA328-P	<input type="checkbox"/>

RTC Circuit

RTC	RTC Module	<input type="checkbox"/>
SV4	CONN_RTC	<input type="checkbox"/>
R19	1k	<input type="checkbox"/>
R23	1k	<input type="checkbox"/>
Q6	MPSA42	<input type="checkbox"/>
TICK LED	LED 5mm	<input type="checkbox"/>
SV6	CONN_LED	<input type="checkbox"/>
SV2	CONN_FRONT	<input type="checkbox"/>
BAT1	CR2032	<input checked="" type="checkbox"/>

(BAT1 not be supplied by post)

Anode Control Circuit

S24	SOCKET 24	<input type="checkbox"/>
OK1	EL817	<input type="checkbox"/>
OK2	EL817	<input type="checkbox"/>
OK3	EL817	<input type="checkbox"/>
OK4	EL817	<input type="checkbox"/>
OK5	EL817	<input type="checkbox"/>
OK6	EL817	<input type="checkbox"/>
R1	1k	<input type="checkbox"/>
R2	1k	<input type="checkbox"/>
R3	1k	<input type="checkbox"/>
R12	1k	<input type="checkbox"/>
R13	1k	<input type="checkbox"/>
R14	1k	<input type="checkbox"/>
R4	3k	<input type="checkbox"/>
R5	3k	<input type="checkbox"/>
R6	3k	<input type="checkbox"/>
R15	3k	<input type="checkbox"/>
R16	3k	<input type="checkbox"/>
R17	3k	<input type="checkbox"/>
SV3	CONN_ANODE	<input type="checkbox"/>

Cathode Control Circuit

IC3	K155ID1	<input type="checkbox"/>
S16	SOCKET 16	<input type="checkbox"/>
SV5	CONN_DIGIT	<input type="checkbox"/>

Front Panel

R20	1k	<input type="checkbox"/>
R21	1k	<input type="checkbox"/>
R22	1k	<input type="checkbox"/>
Q3	2N7000	<input type="checkbox"/>
Q4	2N7000	<input type="checkbox"/>
Q5	2N7000	<input type="checkbox"/>
LDR	GL5516	<input type="checkbox"/>
S1	SWITCH	<input type="checkbox"/>
LED RGB	LED RGB Anode	<input type="checkbox"/>
R11	10k	<input type="checkbox"/>

Revisions:

V0001: 22Jun2017: Split out from instruction and construction manual
V0002: 25Oct2017: Update Tick LED description for V48+, add section for "Time Provider"
V0003: 30Jan2018: Corrected R11 in BoM, small changes to component descriptions
V0004: 29Mar2018: Add note about the HV generation running for only 60s.
V0005: 08Apr2018: Corrected Tick LED connector labeling: Thanks Fred!
V0006: 21May2018: Changed absolute maximum from 24V to 16V
V0007: 07Jul2018: Added note about voltage ratings of C4/C9
V0008: 23Oct2018: Update for differences between 4 and 6 digit build
V0009: 22Aug2019: Correct voltage ratings on C4/C9, thanks Bob!